Binary Search Trees (BSTs)

CS 121: Data Structures

START RECORDING

Attendance Quiz: Sorting

- Scan the QR code, or find today's attendance quiz under the "Quizzes" tab on Canvas
- Password: to be announced
- Sequence: {"z", "b", "a", "c"}

Attendance Quiz: Sorting

- Write your name and the date
- Trace sorting the elements {“z”, “b”, “a”, “c”} in alphabetical ascending order using:
  - Selection sort
  - Insertion sort

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3.2 Binary Search Trees

- *BSTs*
- *ordered operations*
- *deletion*

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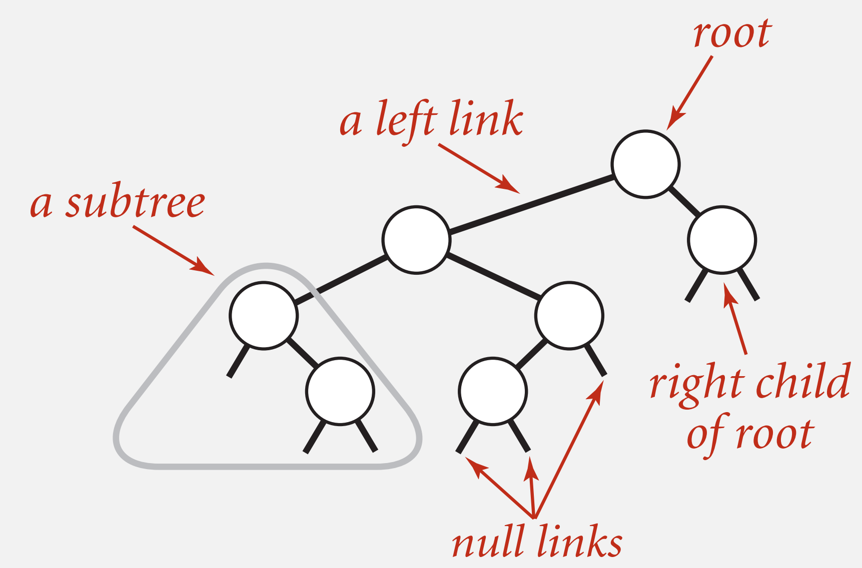
3.2 Binary Search Trees

- *BSTs*
- *ordered operations*
- *deletion*

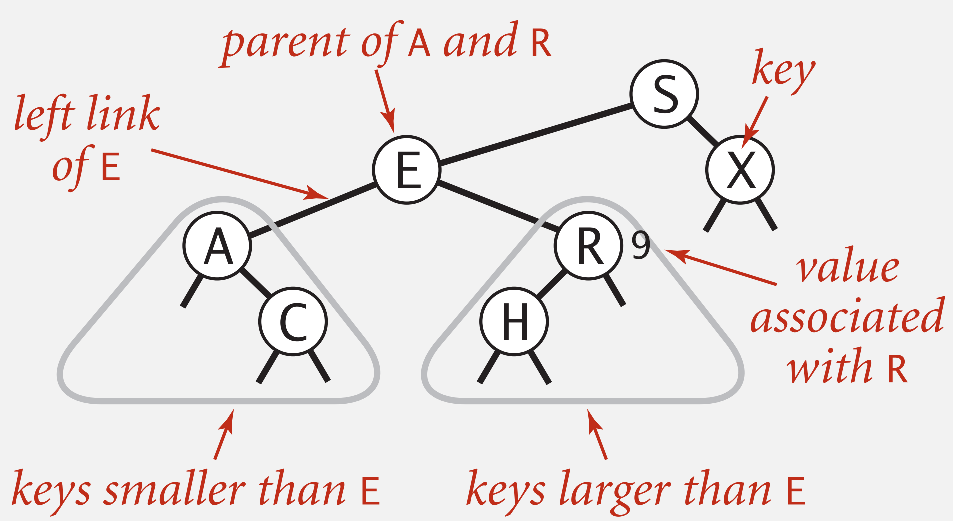
Binary search trees: another implementation of symbol tables

Definition. A BST is a binary tree in symmetric order.

A binary tree is either:
- Empty.
- Two disjoint binary trees (left and right).



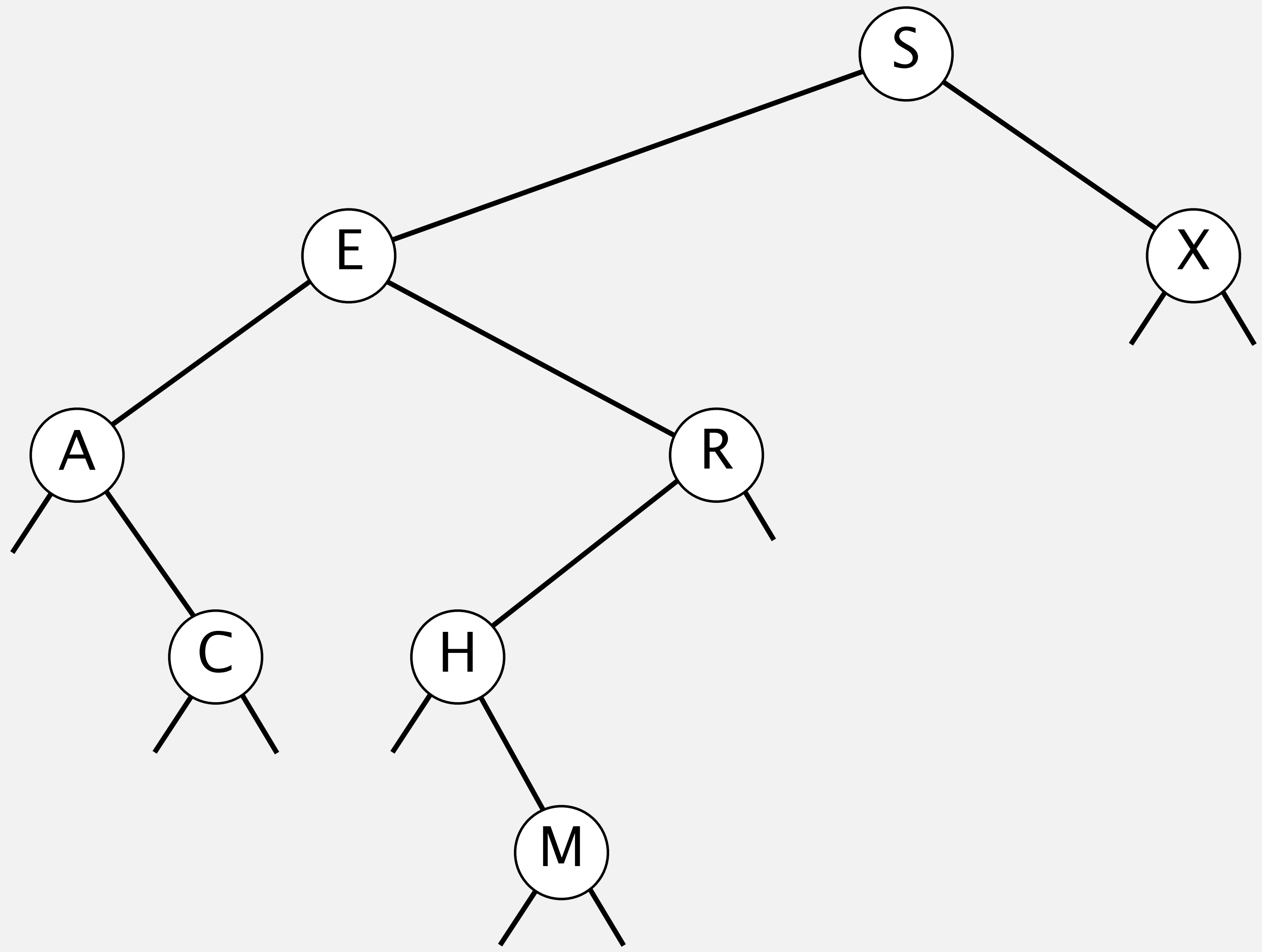
Symmetric order. Each node has a key, and every node's key is:
- Larger than all keys in its left subtree.
- Smaller than all keys in its right subtree.



Binary search tree demo

Search. If less, go left; if greater, go right; if equal, search hit.

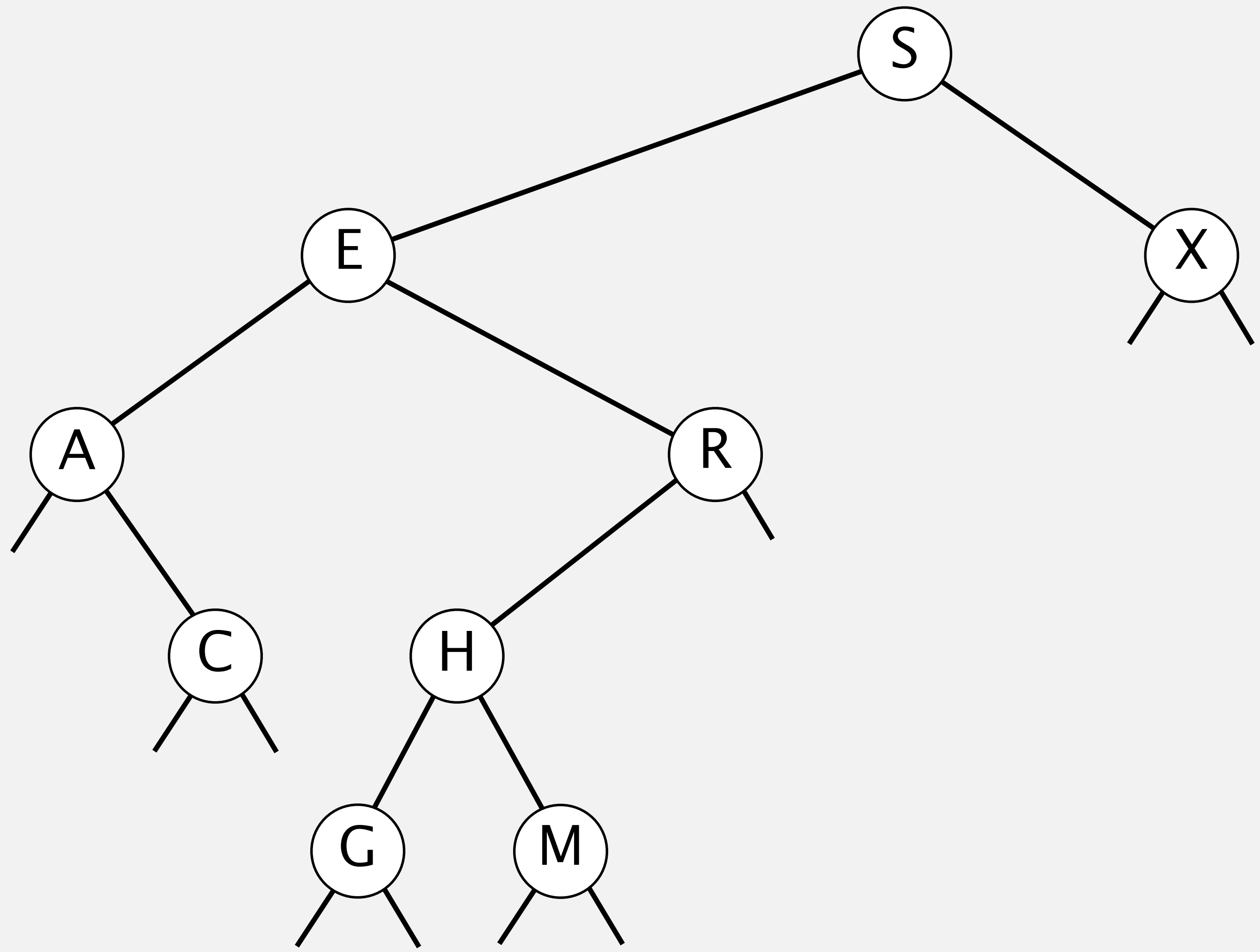
successful search for H



Binary search tree demo

Insert. If less, go left; if greater, go right; if null, insert.

insert G



BST representation in Java

Java definition. A BST is a reference to a root `Node`.

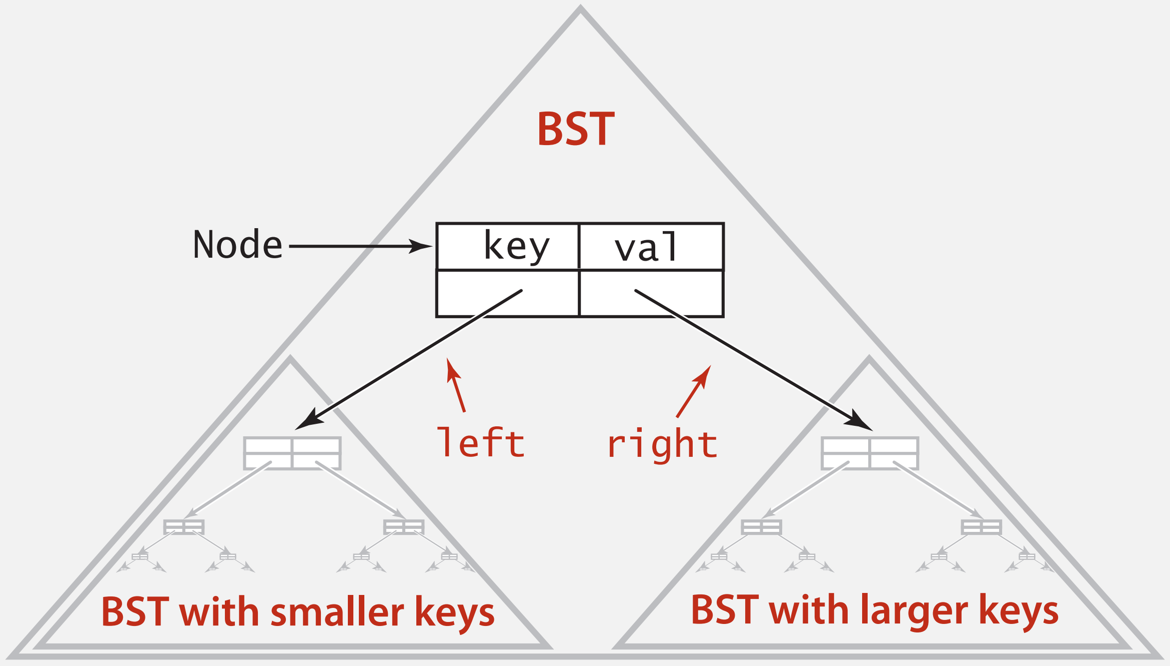
A `Node` is composed of four fields:

- A `Key` and a `Value`.
- A reference to the left and right subtree.

smaller keys   larger keys

```
private class Node
{
   private Key key;
   private Value val;
   private Node left, right;
   public Node(Key key, Value val)
   {
      this.key = key;
      this.val = val;
   }
}
```

Key and Value are generic types; Key is Comparable



Binary search tree

BST implementation (skeleton)

```
public class BST<Key extends Comparable<Key>, Value>
{
    private Node root;

   private class Node
   {  /* see previous slide */  }

   public void put(Key key, Value val)
   {  /* see next slides */  }

   public Value get(Key key)
   {  /* see next slides */  }

   public void delete(Key key)
   {  /* see next slides */  }

   public Iterable<Key> iterator()
   {  /* see next slides */  }

}
```

root of BST

BST search: Java implementation

Get. Return value corresponding to given key, or `null` if no such key.

```
public Value get(Key key)
{
   Node x = root;
   while (x != null)
   {
      int cmp = key.compareTo(x.key);
      if      (cmp  < 0) x = x.left;
      else if (cmp  > 0) x = x.right;
      else if (cmp == 0) return x.val;
   }
   return null;
}
```

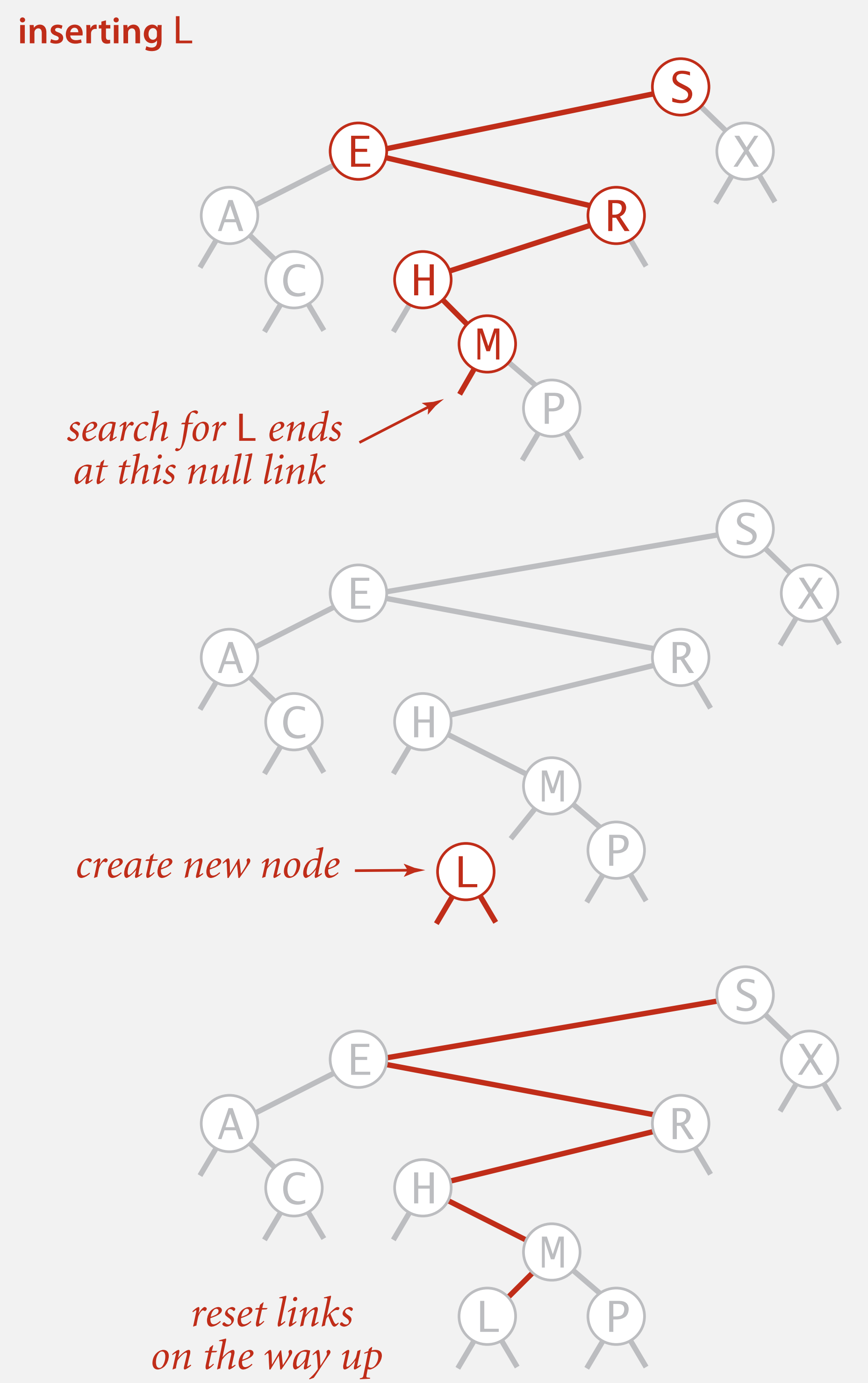
Cost. Number of compares is equal to 1 + depth of node.

BST insert

Put. Associate value with key.

Search for key, then two cases:

- Key in tree $\Rightarrow$ reset value.
- Key not in tree $\Rightarrow$ add new node.



Insertion into a BST

BST insert: Java implementation

Put. Associate value with key.

concise, but tricky, recursive code; read carefully!

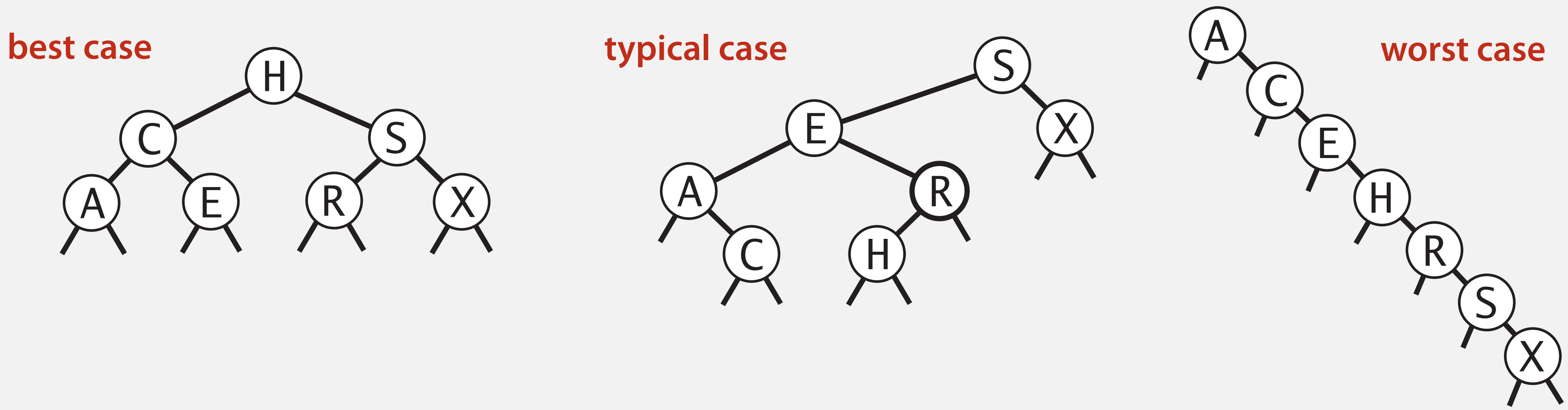
```
public void put(Key key, Value val)
{  root = put(root, key, val);  }

private Node put(Node x, Key key, Value val)
{
   if (x == null) return new Node(key, val);
   int cmp = key.compareTo(x.key);
   if      (cmp  < 0)
      x.left  = put(x.left,  key, val);
   else if (cmp  > 0)
      x.right = put(x.right, key, val);
   else if (cmp == 0)
      x.val = val;
   return x;
}
```

Cost. Number of compares is equal to 1 + depth of node.

Tree shape

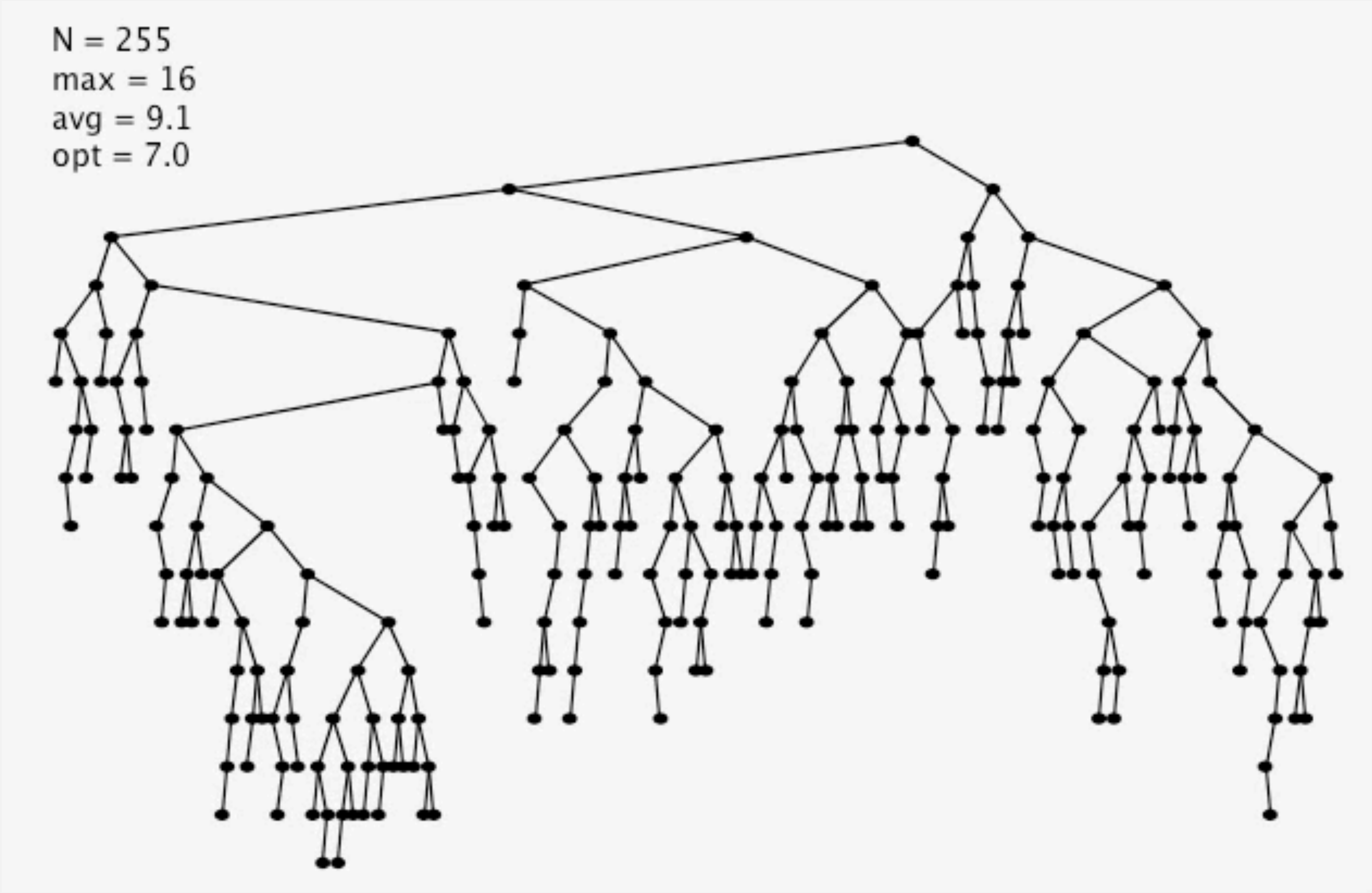
- Many BSTs correspond to same set of keys.
- Number of compares for search/insert is equal to 1 + depth of node.



Bottom line. Tree shape depends on order of insertion.

BST insertion: random order visualization

Ex. Insert keys in random order.



BSTs: mathematical analysis

Proposition. If N distinct keys are inserted into a BST in random order, the expected number of compares for a search/insert is $\sim 2 \ln N$.

Pf. 1–1 correspondence with quicksort partitioning.

Proposition. [Reed, 2003] If N distinct keys are inserted in random order, expected height of tree is $\sim 4.311 \ln N$.

How Tall is a Tree?

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ABSTRACT

Let H_n be the height of a random binary search tree on n nodes. We show that there exists constants $\alpha = 4.31107\ldots$ and $\beta = 1.95\ldots$ such that $\mathrm{E}(H_n) = \alpha \log n - \beta \log\log n + O(1)$, We also show that $\mathrm{Var}(H_n) = O(1)$.

But... Worst-case height is $N - 1$.

[exponentially small chance when keys are inserted in random order]

ST implementations: summary

implementation	guarantee		average case		operations on keys
	search	insert	search hit	insert	
sequential search (unordered list)	N	N	½ N	N	`equals()`
binary search (ordered array)	lg N	N	lg N	½ N	`compareTo()`
separate chaining hash table	N	N	3-5	3-5	`equals()` `hashCode()`
linear probing hash table	N	N	3-5	3-5	`equals()` `hashCode()`
BST	N	N	1.39 lg N	1.39 lg N	`compareTo()`

Given all the data, we could shuffle to ensure a (probabilistic) guarantee of 4.311 ln N. However, a probabilistic guarantee isn't really a *guarantee*, and we don't always have all the data up front.

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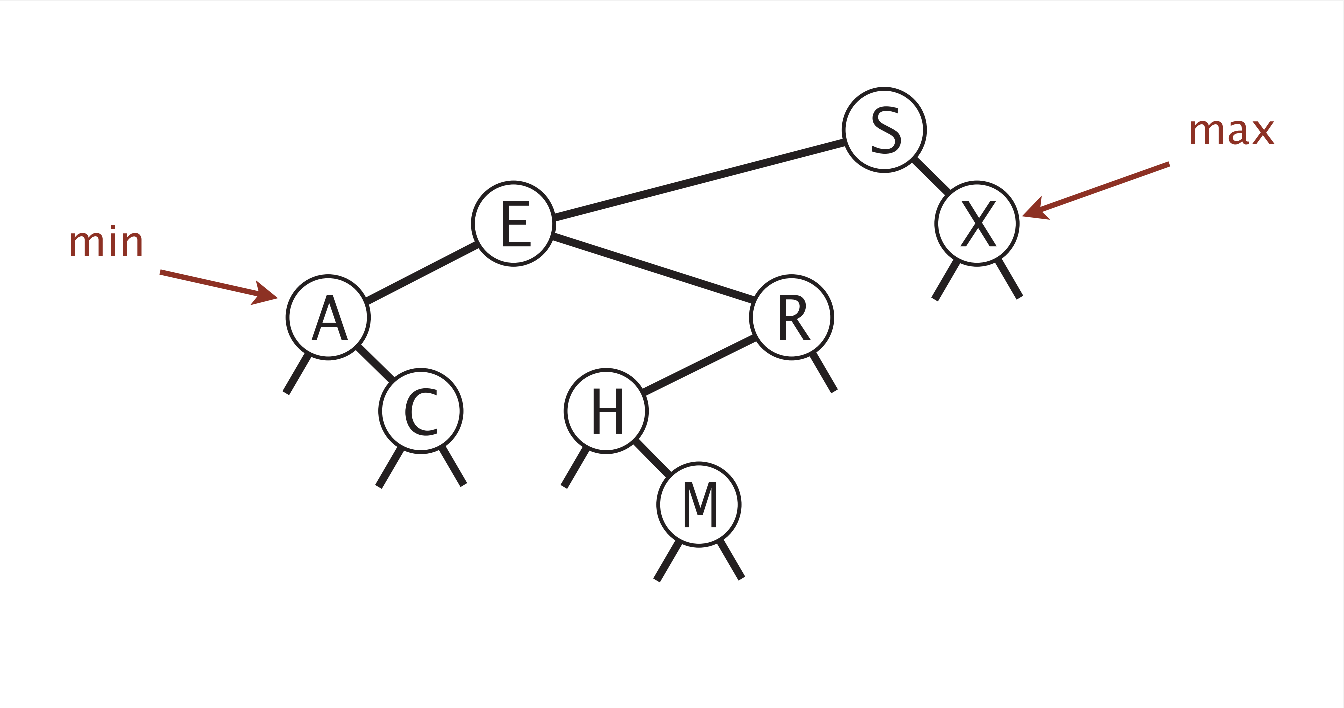
3.2 Binary Search Trees

- BSTs
- *ordered operations*
- deletion

Minimum and maximum

Minimum. Smallest key in table.

Maximum. Largest key in table.



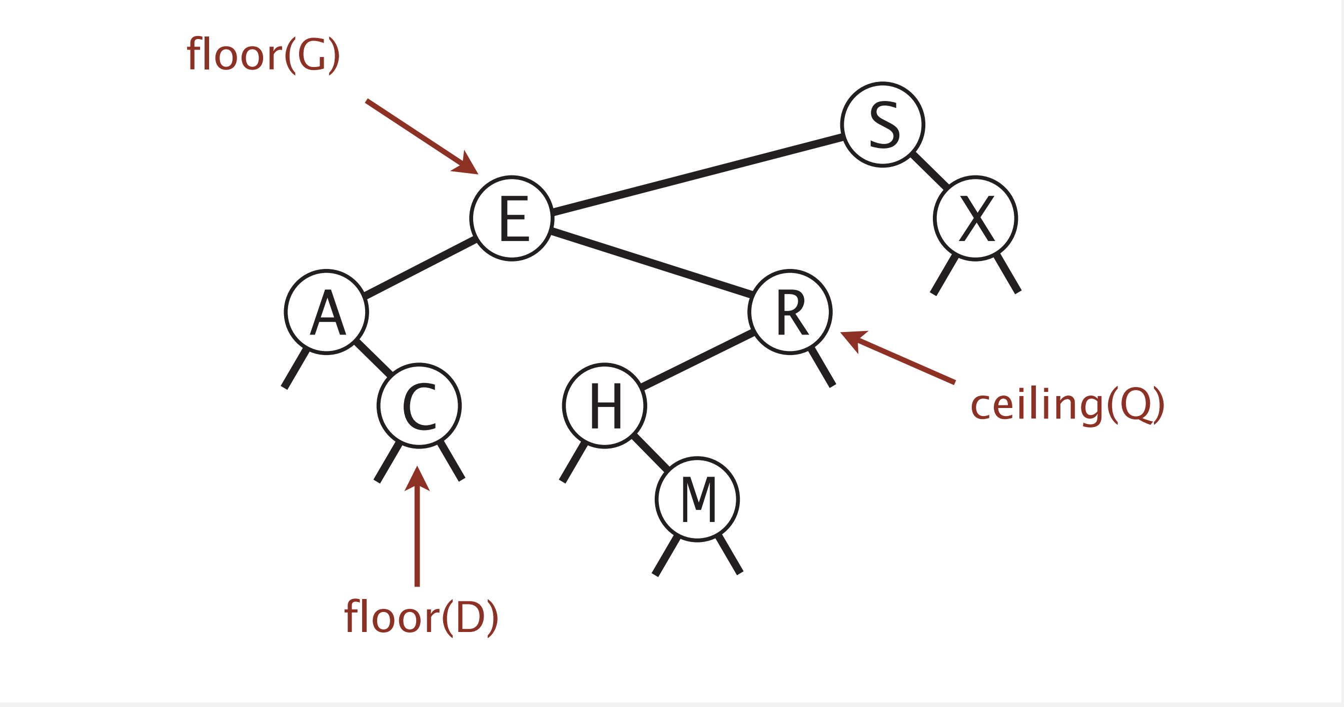
Q. How to find the min / max?

Floor and ceiling

Floor. Largest key ≤ a given key.

Ceiling. Smallest key ≥ a given key.

Q. How to find the floor / ceiling?



Easy, if the keys were sorted in an array

A	C	E	H	M	R	S	X

Computing the floor

Case 1. [k equals the key in the node]

The floor of k is k.

Case 2. [k is less than the key in the node]

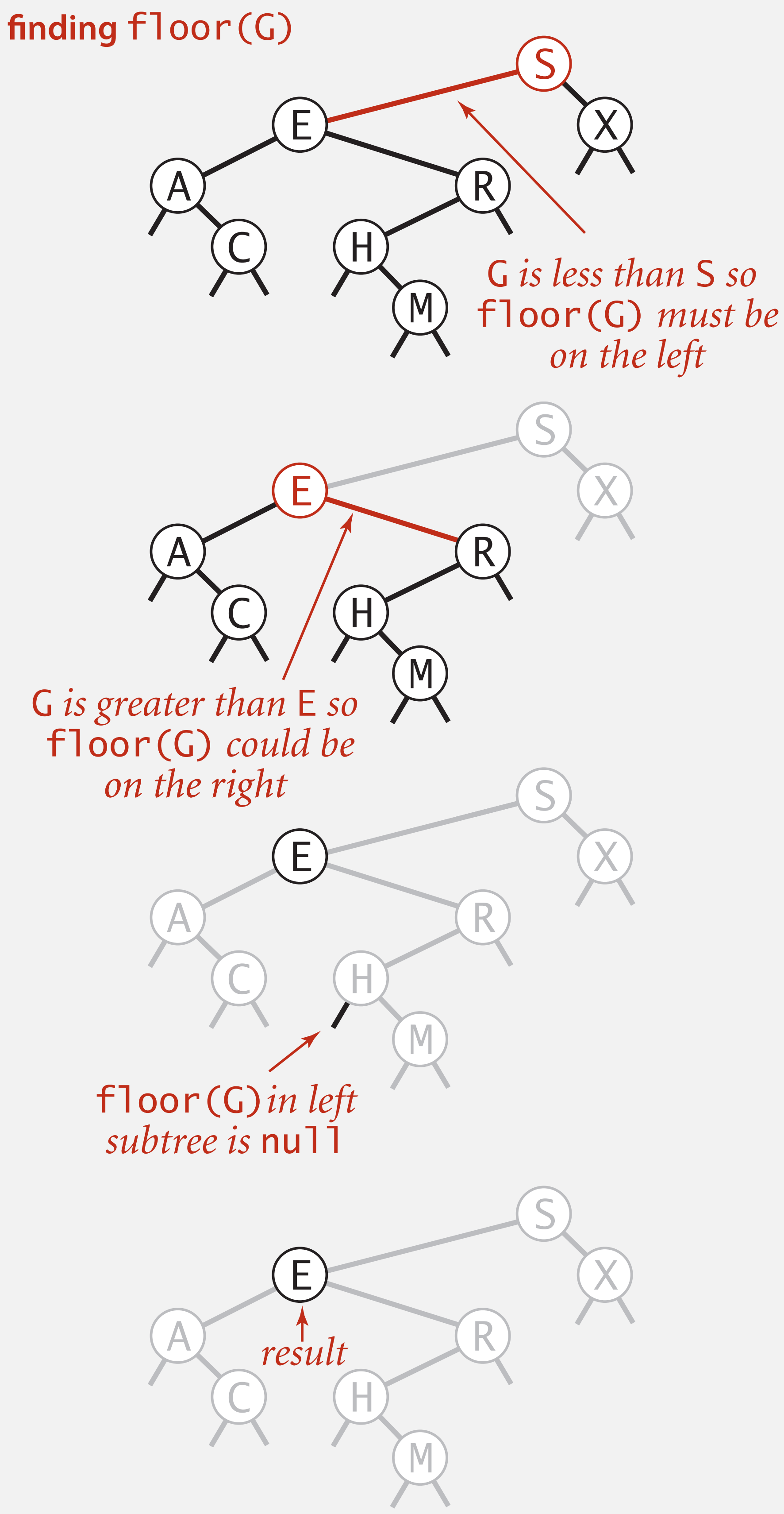
The floor of k is in the left subtree.

Case 3. [k is greater than the key in the node]

The floor of k is in the right subtree

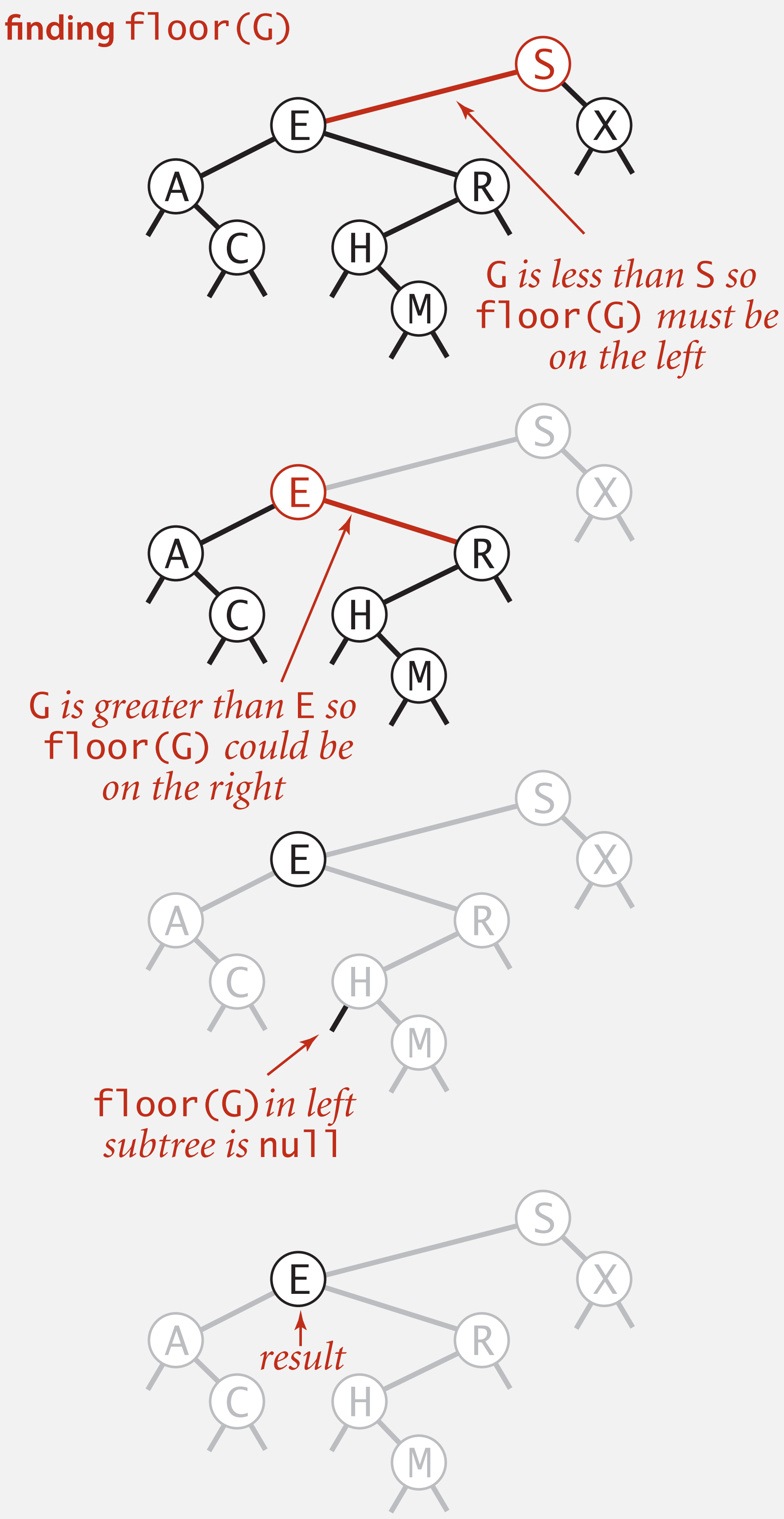
(if there is any key ≤ k in right subtree);

otherwise it is the key in the node.



Computing the floor

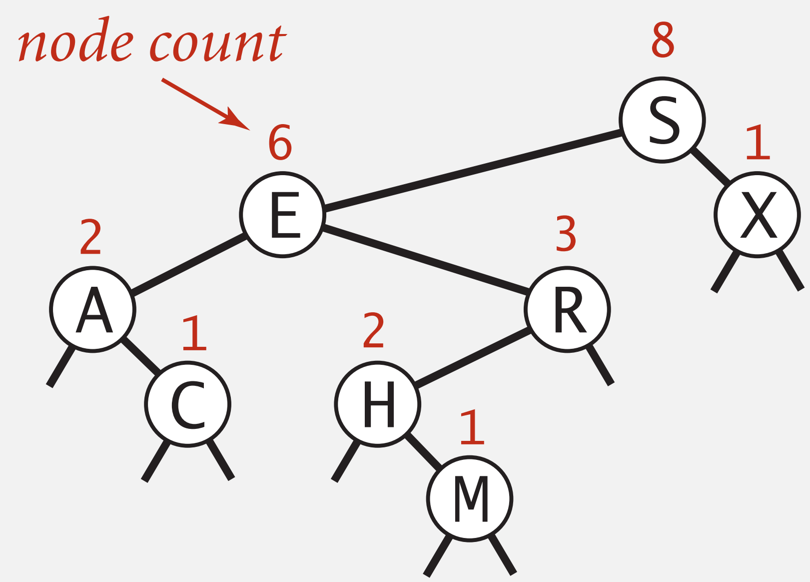
```
public Key floor(Key key)
{
   Node x = floor(root, key);
   if (x == null) return null;
   return x.key;
}
private Node floor(Node x, Key key)
{
   if (x == null) return null;
   int cmp = key.compareTo(x.key);

   if (cmp == 0) return x;

   if (cmp < 0)  return floor(x.left, key);

   Node t = floor(x.right, key);
   if (t != null) return t;
   else           return x;

}
```



Rank and select

Q. How to implement `rank()` and `select()` efficiently?

A. In each node, we store the number of nodes in the subtree rooted at that node; to implement `size()`, return the count at the root.



Easy, if the keys were sorted in an array

A	C	E	H	M	R	S	X
1	2	3	4	5	6	7	8

BST implementation: subtree counts

```
private class Node
{
   private Key key;
   private Value val;
   private Node left;
   private Node right;
   private int count;
}
```

number of nodes in subtree

```
public int size()
{  return size(root);  }
```

```
private int size(Node x)
{
   if (x == null) return 0;
   return x.count;
}
```

ok to call when x is null

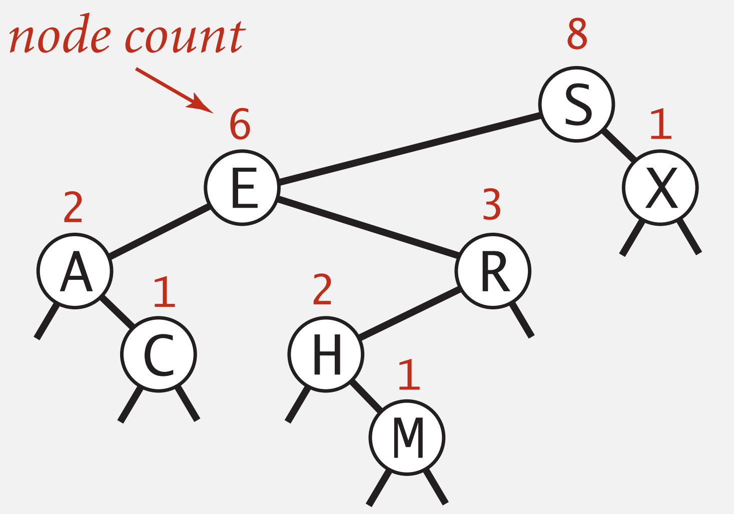
```
private Node put(Node x, Key key, Value val)
{
   if (x == null) return new Node(key, val, 1);
   int cmp = key.compareTo(x.key);
   if      (cmp  < 0) x.left  = put(x.left,  key, val);
   else if (cmp  > 0) x.right = put(x.right, key, val);
   else if (cmp == 0) x.val = val;
   x.count = 1 + size(x.left) + size(x.right);
   return x;
}
```

initialize subtree count to 1

Rank

Rank. How many keys < k ?

Easy recursive algorithm (3 cases!)

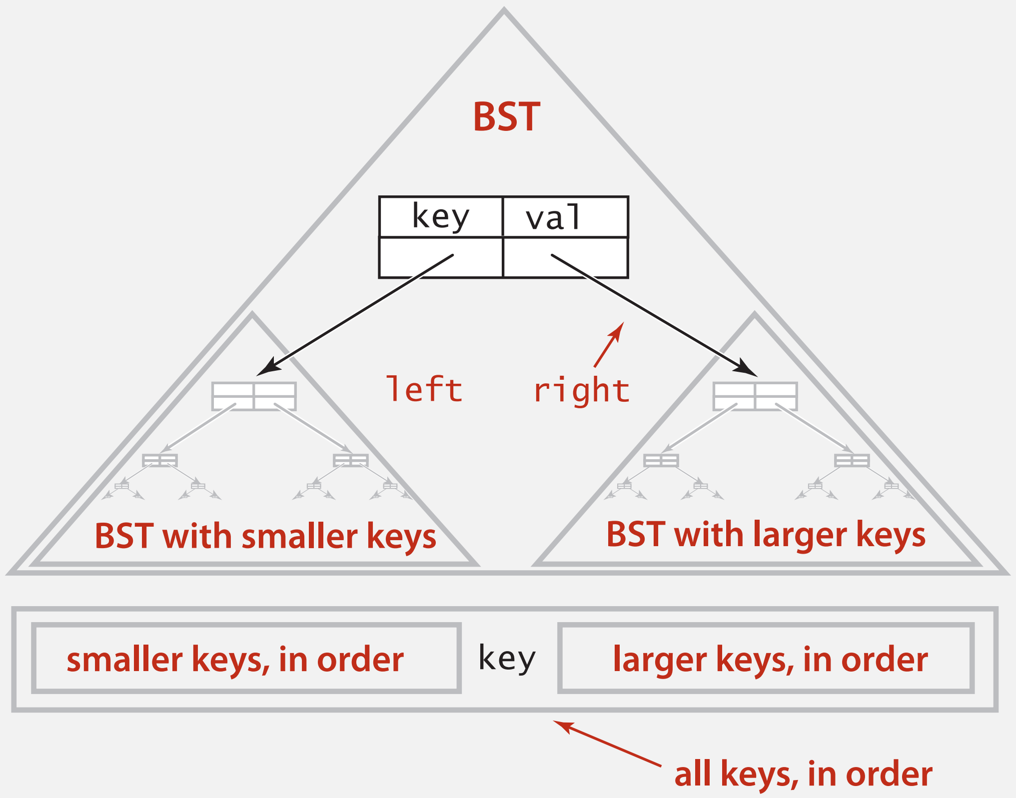



```
public int rank(Key key)
{  return rank(key, root);  }

private int rank(Key key, Node x)
{
   if (x == null) return 0;
   int cmp = key.compareTo(x.key);
   if      (cmp  < 0) return rank(key, x.left);
   else if (cmp  > 0) return 1 + size(x.left) + rank(key, x.right);
   else if (cmp == 0) return size(x.left);
}
```

Inorder traversal

- Traverse left subtree.
- Enqueue key.
- Traverse right subtree.

```
public Iterable<Key> keys()
{
    Queue<Key> q = new Queue<Key>();
    inorder(root, q);
    return q;
}

private void inorder(Node x, Queue<Key> q)
{
   if (x == null) return;
   inorder(x.left, q);
   q.enqueue(x.key);
   inorder(x.right, q);
}
```



Property. Inorder traversal of a BST yields keys in ascending order.

BST: ordered symbol table operations summary

	unordered list (sequential search)	ordered array (binary search)	BST
search	N	$\lg N$	h
insert	N	N	h
min / max	N	1	h
floor / ceiling	N	$\lg N$	h
rank	N	$\lg N$	h
select	N	1	h
ordered iteration	$N \log N$	N	N

order of growth of running time of ordered symbol table operations

h = height of BST
(proportional to log N
if keys inserted in random order)

Attendance Quiz: BST Insertion

- Scan the QR code, or find today's attendance quiz under the "Quizzes" tab on Canvas
- Password: to be announced
- Keys:
  A D G H B C E F

Attendance Quiz: BST Insertion

- Write your name and the date
- Draw a binary search tree containing the following keys, inserted in the listed order:
    - A D G H B C E F

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3.2 Binary Search Trees

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ST implementations: summary

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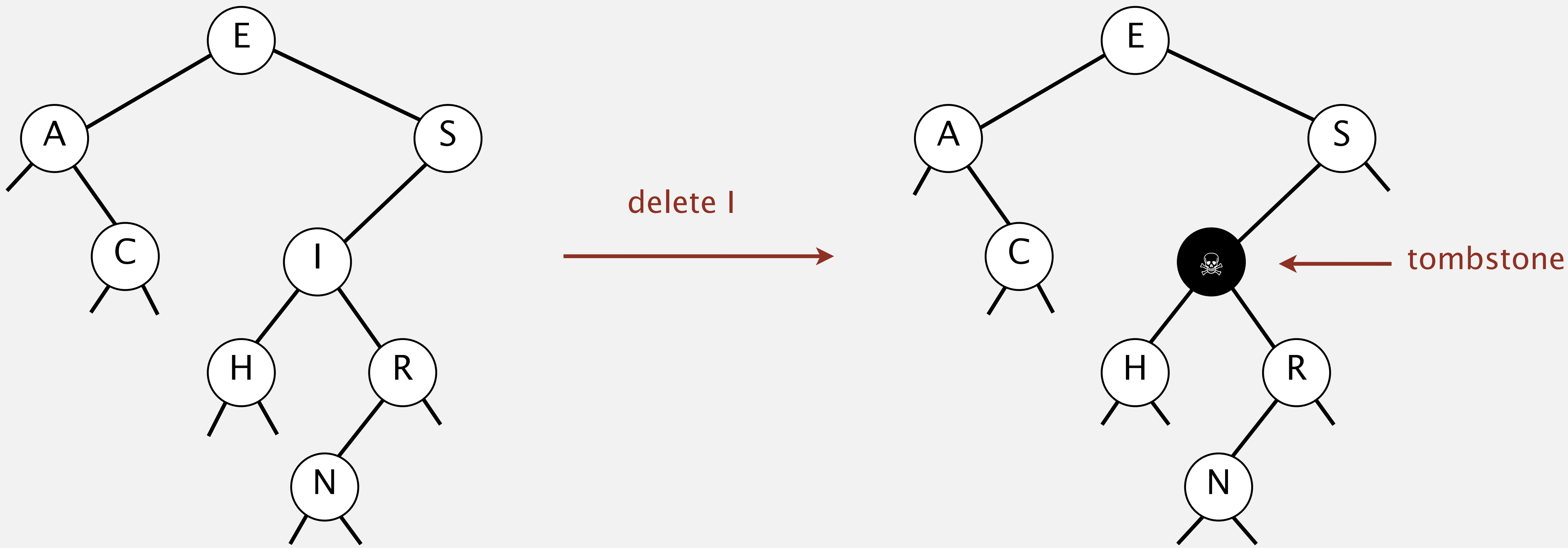
	search	insert	delete	search hit	insert	delete		
sequential search (linked list)	N	N	N	½ N	N	½ N		equals()
binary search (ordered array)	lg N	N	N	lg N	½ N	½ N	✔	compareTo()
separate chaining hash table	N	N	N	3-5	3-5	3-5		equals() hashCode()
linear probing hash table	N	N	N	3-5	3-5	3-5		equals() hashCode()
BST	N	N	N	1.39 lg N	1.39 lg N	? ? ?	✔	compareTo()

Next. Deletion in BSTs.

BST deletion: lazy approach

To remove a node with a given key:

- Set its value to `null`.
- Leave key in tree to guide search (but don't consider it equal in search).



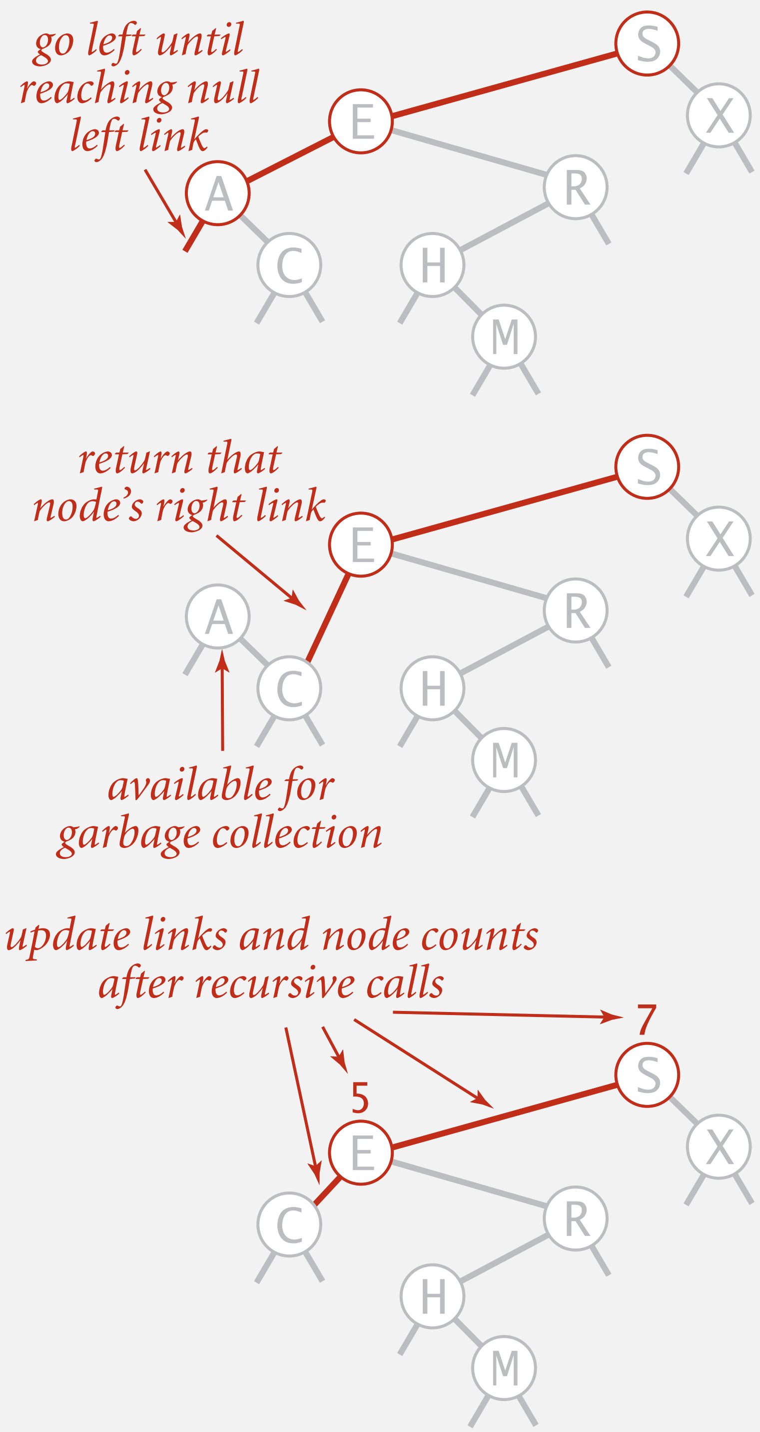
Cost. $\sim 2 \ln N'$ per insert, search, and delete (if keys in random order), where N' is the number of key-value pairs ever inserted in the BST.

Unsatisfactory solution. Tombstone (memory) overload.

Deleting the minimum

To delete the minimum key:

- Go left until finding a node with a null left link.
- Replace that node by its right link.
- Update subtree counts.



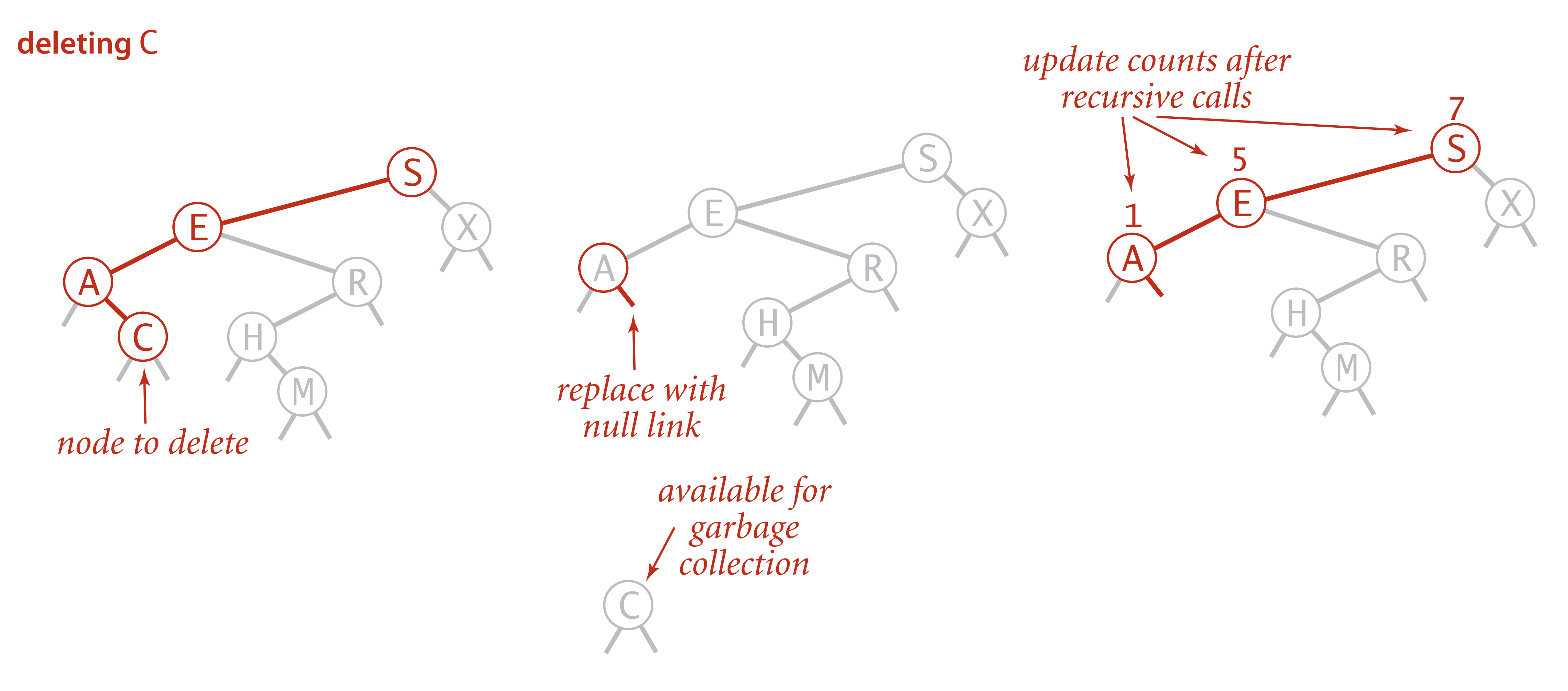

```
public void deleteMin()
{  root = deleteMin(root);  }

private Node deleteMin(Node x)
{
   if (x.left == null) return x.right;
   x.left = deleteMin(x.left);
   x.count = 1 + size(x.left) + size(x.right);
   return x;
}
```

Hibbard deletion

To delete a node with key `k`: search for node `t` containing key `k`.

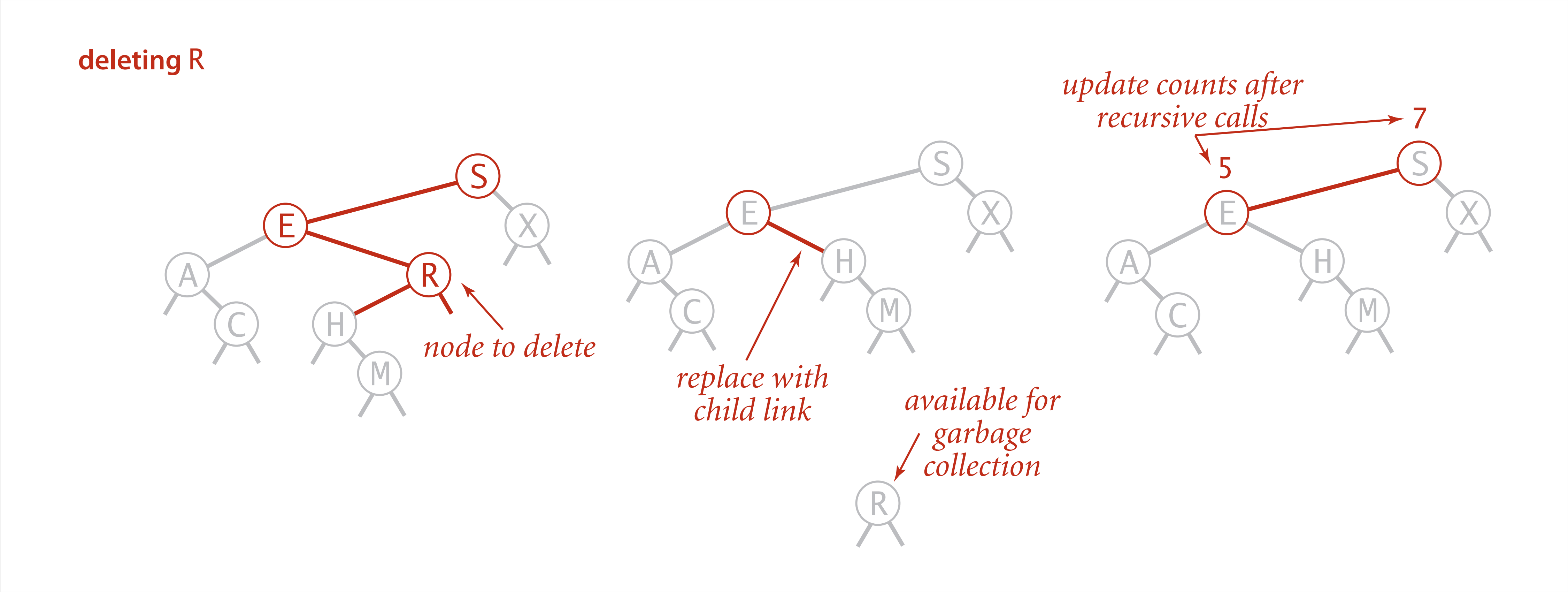
Case 0. [0 children] Delete `t` by setting parent link to null.



Hibbard deletion

To delete a node with key `k`: search for node `t` containing key `k`.

Case 1. [1 child] Delete `t` by replacing parent link.

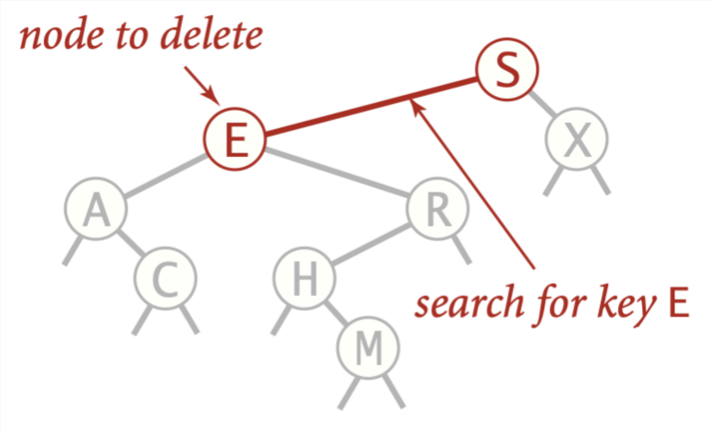


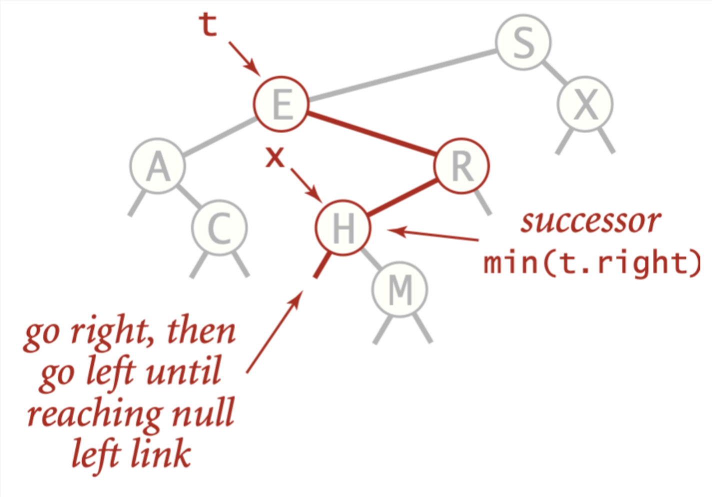
Hibbard deletion

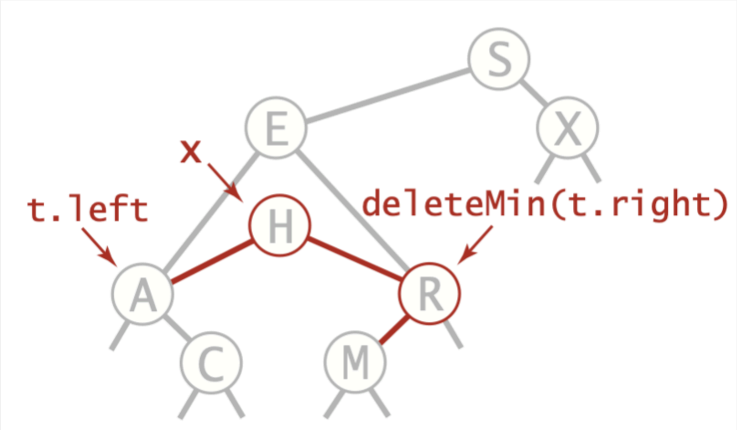
To delete a node with key `k`: search for node `t` containing key `k`.

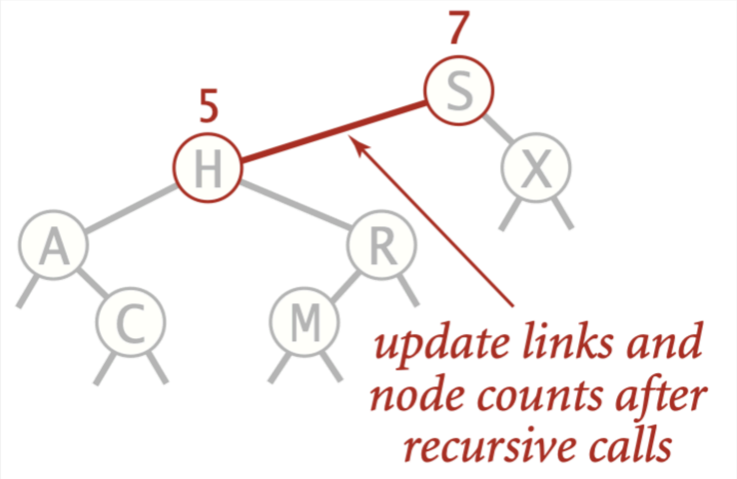
Case 2. [2 children]

- Find successor `x` of `t`. ← x has no left child
- Delete the minimum in `t`'s right subtree. ← but don't garbage collect x
- Put `x` in `t`'s spot. ← still a BST









Hibbard deletion: Java implementation

```
public void delete(Key key)
{  root = delete(root, key);  }

private Node delete(Node x, Key key) {
   if (x == null) return null;
   int cmp = key.compareTo(x.key);
   if      (cmp < 0) x.left  = delete(x.left,  key);
   else if (cmp > 0) x.right = delete(x.right, key);
   else {
      if (x.right == null) return x.left;
      if (x.left  == null) return x.right;

      Node t = x;
      x = min(t.right);
      x.right = deleteMin(t.right);
      x.left = t.left;
   }
   x.count = size(x.left) + size(x.right) + 1;
   return x;
}
```

search for key

no right child

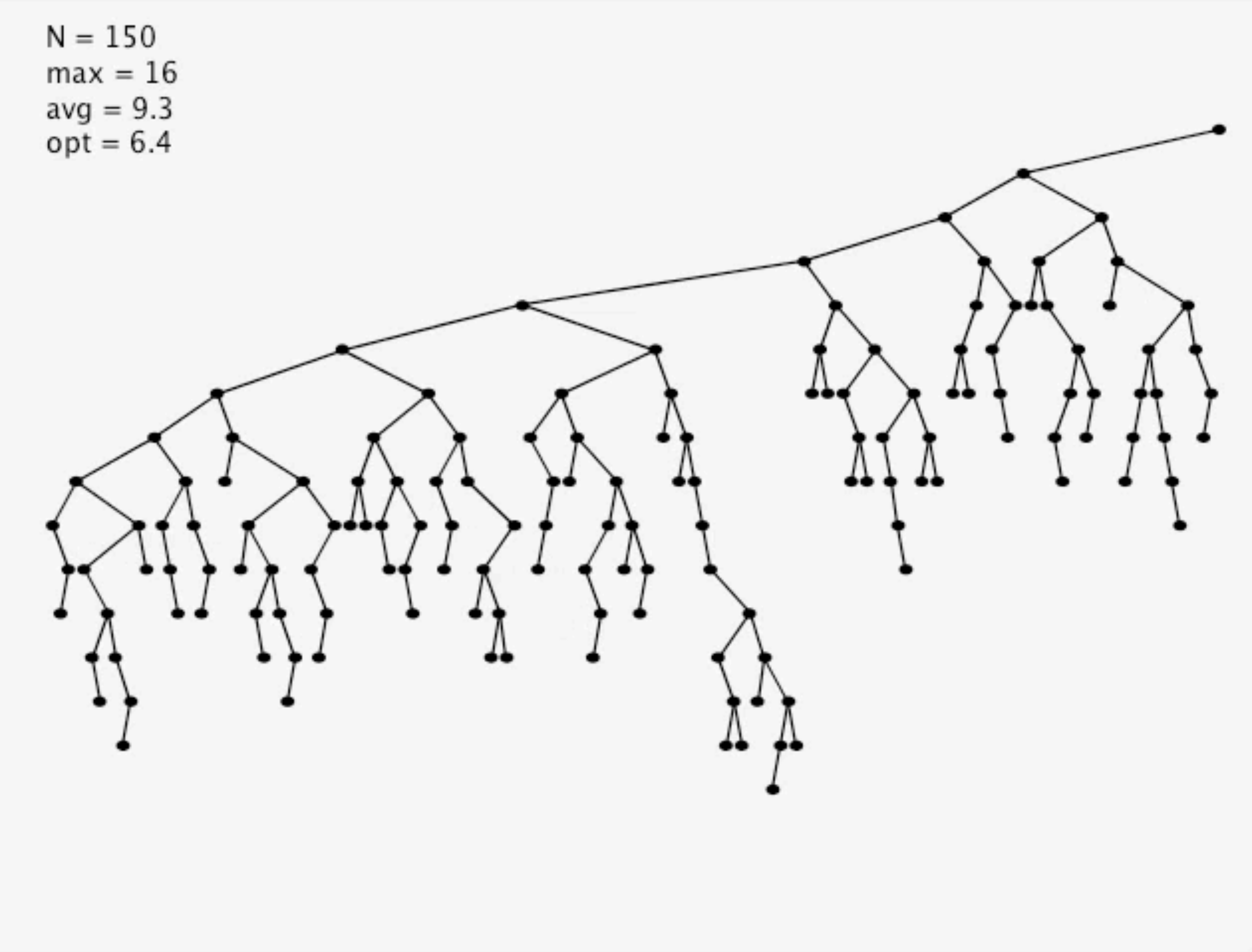
no left child

replace with successor

update subtree counts

Hibbard deletion: analysis

Unsatisfactory solution. Not symmetric.



Surprising consequence. Trees not random (!) $\Rightarrow$ $\sqrt{N}$ per op.

Longstanding open problem. Simple and efficient delete for BSTs.

ST implementations: summary

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BST	N	N	N	1.39 lg N	1.39 lg N	$\sqrt{N}$	✔	`compareTo()`

other operations also become √N
if deletions allowed

Next lecture. Guarantee logarithmic performance for all operations, using *balanced* search trees.